

**SSR DEGREE COLLEGE (AUTONOMOUS) NIZAMABAD**  
**SEM –I INTERNAL – II**  
**M.SC. PHYSICS**  
**(mathematical physics)**  
**QUESTION BANK**

## **I. Multiple Choice Questions**

1. The bisection method is based on which theorem?  
A) Taylor's theorem      B) Rolle's theorem      C) Intermediate Value Theorem  
D) Mean Value Theorem  
Answer: C
2. The bisection method can be applied only if:  
A)  $f(x)$  is differentiable      B)  $f(x)$  is continuous and changes sign in the interval  
C)  $f(x)$  is increasing      D)  $f(x)$  is polynomial  
Answer: B
3. The forward difference quotient is used to approximate:  
A) Integration      B) Second derivative      C) First derivative      D) Root of equation  
Answer: C
4. Central difference quotient is not suitable at:  
A) Boundary points      B) Interior points      C) Smooth functions      D) Uniform data  
Answer: A
5. Central difference quotient gives better accuracy than forward difference because:  
A) It uses two step sizes      B) It cancels even-order error terms  
C) It uses backward expansion only      D) It requires smaller data  
Answer: B
6. Newton–Cotes formulas are obtained using:  
A) Taylor series      B) Newton's interpolation      C) Lagrange interpolation  
D) Finite differences  
Answer: C
7. Simpson's 1/3 rule requires the number of subintervals to be:  
A) Odd      B) Prime      C) Even      D) Multiple of 3  
Answer: C
8. Simpson's 3/8 rule requires number of subintervals to be:  
A) Even      B) Odd      C) Multiple of 2      D) Multiple of 3  
Answer: D
9. Simpson's 3/8 rule is generally used when:  
A) Number of intervals is even      B) Number of intervals is a multiple of 3

C) Function is discontinuous      D) End points are unknown

Answer: B

10. The Taylor series method is mainly used to solve:

A) Algebraic equations      B) Linear equations  
C) Ordinary differential equations      D) Partial differential equations

Answer: C

11. Muller's method fails mainly when

A. Roots are complex      B. Initial approximations are poor  
C. Function is polynomial      D. Function is continuous

Answer: B

12. Muller's method can find

A. Only real roots      B. Only rational roots      C. Only irrational roots  
D. Both real and complex roots

Answer: D

13. The two-point Gauss-Legendre quadrature is exact for polynomials up to degree

A) 1      B) 2      C) 3      D) 4

Answer: C

14. In Gaussian quadrature, the weights and nodes are chosen to

A) Minimize truncation error      B) Simplify computations  
C) Maximize degree of exactness      D) Reduce round-off errors

Answer: C

15. How many initial approximations are required in the secant method?

a) One      b) Two      c) Three      d) None

Answer: b

16. A second-rank tensor transforms with

A) One transformation matrix      B) Two transformation matrices  
C) Three matrices      D) Determinant only

Answer: B) Two transformation matrices

17. Two tensors can be added if they have

A) Same magnitude      B) Same rank and type  
C) Same components      D) Same units only

Answer: B) Same rank and type

18. The sum of two second-rank tensors is a

A) Scalar      B) Vector      C) Second-rank tensor      D) Third-rank tensor

Answer: C) Second-rank tensor

19. The number of independent components of a symmetric second-rank tensor in 3 dimensions is

A) 3      B) 6      C) 9      D) 1

Answer: B

20. Which of the following is an example of an antisymmetric tensor in physics?

- A) Stress tensor
- B) Moment of inertia tensor
- C) Angular momentum tensor
- D) Metric tensor

Answer: C

## II. Fill in the blanks

1. Euler method requires only the \_\_\_\_ derivative of the function. First
2. Euler method is less accurate because it neglects \_\_\_\_ order terms. Higher
3. In fourth-order Runge–Kutta method, the number of intermediate slopes used is \_\_\_\_  
Four
4. Runge–Kutta method uses \_\_\_\_ slopes to improve accuracy. Multiple
5. The weight factors in Gaussian quadrature are obtained from \_\_\_\_ polynomials.  
Orthogonal
6. The total error in numerical differentiation is the sum of \_\_\_\_ error and \_\_\_\_ error.  
Truncation, round-off
7. Regula–Falsi method is a combination of \_\_\_\_ and \_\_\_\_ methods. Bisection, Secant
8. Root finding methods are mainly applied to \_\_\_\_ equations. Nonlinear
9. Increasing the number of terms in Taylor series expansion \_\_\_\_ the accuracy. Increases
10. Taylor series method generally gives \_\_\_\_ accuracy than Euler's method. Higher
11. Contravariant tensor components are usually written with \_\_\_\_ indices. **Answer: upper**
12. The scalar product of a covariant and contravariant vector results in a \_\_\_\_.  
**Answer: scalar**
13. The conductivity of a crystal in solid-state physics is expressed as a \_\_\_\_ tensor.  
**(second-order)**
14. In general relativity, gravitation is described using the \_\_\_\_ tensor. **(metric / Einstein)**
15. A covariant tensor of second order transforms with the \_\_\_\_ of the Jacobian matrix.  
**(square of the inverse)**
16. The transformation law ensures that tensor equations are \_\_\_\_ independent.  
**(coordinate)**
17. 7. The metric tensor is denoted by \_\_\_\_
18. 8. In Cartesian coordinates, the metric tensor components are -----
19. Addition and subtraction of tensors do not affect their \_\_\_\_ law. **Transformation**
20. Tensor addition is \_\_\_\_ and associative.

### **III. Descriptive Questions**

1. Solve an ODE using runge kutta forth order method
2. find a real root of the equation using bisection method correct to 3 decimal
3. explain addition ,subtraction and outer product of tensors
4. expain contraction and inner product of tensors
5. what are symmetric and anti symmetric tensors
6. what is Muller's method