## TELANGANA UNIVERSITY S.S.R. DEGREE COLLEGE, NIZAMABAD (C.C:5029) V SEMESTER INTERNAL ASSESSMENT I EXAMINATIONS LINEAR ALGEBRA QUESTION BANK

I. Multiple choice questions.						
1. If a subspace of a vector space V is a subset H of V then						
a. Zero vector of V is in H	ctor addition					
c. H is closed under multiplication by scalars	d. All the above					
2. If A = $[a_1, a_2, \dots, a_n]$ then ColA =		[c]				
a. $[a_1, a_2, \dots, a_n]$ b. $\{x:x \text{ is in } \mathbb{R}^n\}$	c. Span $\{a_1, a_2,, a_n\}$	d. None of theses				
3. If T is a linear transformation from a vector	space V into a vector space W th	nen [c]				
a. T(u+v) = T(u)+T(v) $\forall$ u. v $\in$ V and scalar c	b. Both a & b	d. None of these				
4 An indexed set of vectors $\{v_4, v_2, \dots, v_n\}$ in V is	s said to linearly independent if	$C_1V_1+C_2V_2+C_2V_2=0$				
has only		[a]				
a Trivial solution h Non-trivial solution	n c No solution	d rational solution				
5. If $B = \{h_1, h_2, \dots, h_n\}$ is a basis for a vector	snace V then the coordinate ma	nning $x \rightarrow [x]_{a}$ is				
$\int \frac{1}{2} \int $	space v then the coordinate ma	[b]				
	c Roth a & h	d Nono of those				
a. Onco $D$ . One-one c. Let $D = \{b, b, c, c,$		ists a unique set of scalars				
<b>b.</b> Let $B = \{D_1, D_2, \dots, D_n\}$ be basis for a vector	space v. For each xev, there ex	ists a unique set of scalars				
$c_1, c_2, \dots, c_n$ such that $x = c_1 b_1 + c_2 b_2 + \dots + c_n$	b <sub>n</sub> . This is called	[d]				
a. Spanning set theorem b. Basis theorem	c. Rank theorem d. Uniq	ue representation theorem				
7. H is subspace of V and B = $\{b_1, b_2, \dots, b_n\}\epsilon^{T}$	V is a basis for H if	[C]				
a. B is a linearly independent set b. H –	- Span $\{b_1, b_2, \dots, b_n\}$ c. Both	a & b d. None of these				
8. If V is a vector space and u, v and weV and c	,d are scalars then	[d]				
a. $u+v \in V$ b. $(u+v)+w = u+(v+w)$	) c. (c+d)u-cu + du	d. All the above				
9. Col A – R <sup>III</sup> if and only if the equation		[a]				
a. Ax = b has a solution $\forall$ beR <sup>III</sup> b. Ax = 0 has	only the trivial solution c. Nul A	= {0} d. All the above				
10. If vector space V is not spanned by a finite	set then V is said to be	[b]				
a. Finite dimensional b. Infinite dimensional	c. Finite and infinite dimensio	nal d. None of these				
11. The dimensions of the column space and the	he row space of an m x n matrix	A are [a]				
a. Equal b. Unequal c. Can't be said d. approximately equal						
12. A is an invertible matrix of order n x n then	1	[d]				
a. Col A = $R^n$ b. dim Col A = n	c. rank A = n d. All th	e above				
13. If A is an n x n matrix then A is invertible if	and only if	[c]				
a. The number 0 is not an eigen value of A	b. The determinant of	A is not zero				
c. Both a & b d. None of these						
14. If A and B are n x n matrices then		[d]				
a. A is invertible if and only if det $A \neq 0$ b. $ AB $	B  =  A  B  c. $ A'  =  A $	d. All the above				
15. If matrix A of order n x n is invertible then.		[c]				
a. $ AB  =  A  B $		b. $ A  = 0$				
c. A row replacement operation on A does not	change of determinant	d. None of these				
16. If A is a 8 X 9 matrix with two dimensional	null space then the rank of A is	[c]				
a. 5 b. 6	c. 7	d. 8				
17 If A is an invertible matrix of order 8 X 8 Th	hen dim Col A =	[4]				
a 6 h 7		4 8 [~]				
[1 2 0]	0.0	0.0				
18. A = $\begin{bmatrix} 2 & - \\ 0 & 2 & 6 \end{bmatrix}$ . The eigen values of A are		[b]				
		[~]				
a. 1,2,0 b. 1,2,3	c. 1,0,0	d. 0,6,3				

19. A =	1 0 .0	2 4 0	3 6, 5	AE	B  = 60. Then $ B  = 60$		[c]
a. 6					b. 2	c. 3	d. Can't be determined
20. A =	1	0	-1	2			
	0	2	4	5			[a]
	0	0	3	6	. men  A  —		
	0	0	0	4			
a. 24					b. 0	c. 10	d. Doesn't exists

II. Fill in the blanks

1. The set consisting of only the zero vector space V is a subspace of V, called the zero subspace

2. If  $v_1$ ,  $v_2$  are in vector space V and H = span { $v_1$ ,  $v_2$ } then H is a <u>Subspace</u> of V

3. The null space of an m x n matrix A, is the set of all solutions to the Homogeneous equations Ax = 0

4. The <u>null space</u> of an m x n matrix A is a subspace of R<sup>n</sup>

5. The column space of an m x n matrix A is a subspace of R<sup>m</sup>

6. The pivot columns of a matrix A from a basis for Col A

7. Nul A = {0} if and only if the equation Ax = 0 has only the Trivial solution

8. The range of T is the set of all vectors in W of the form T(x) for xeV

9. Nul A = {0} if and only if the linear transformation  $x \rightarrow Ax$  is <u>One-one</u>

10. If vector space V has a basis  $B = \{b_1, b_2, \dots, b_n\}$  then any set in V containing more then n vectors must be <u>Linearly dependent</u>

11. If two matrices A and B are <u>row equivalent</u> then their row spaces are the same.

12. The rank of A is the dimension of the column space of A

13. If A is an m X n matrix then, rank A + dim Nul A =  $\underline{n}$ 

14. A non-zero vector x of a matrix A such that  $Ax = \lambda x$  for scalar  $\lambda$  is called an Eigen vector

15. A scalar  $\lambda$  is called an Eigen value of A if there is a non-trivial solution x of Ax =  $\lambda$  x

16. The eigen values of triangular matrix are the entries on its <u>main diagonal</u>

17. If  $v_1$ ,  $v_2$ , ...... $v_r$  are eigen vectors that correspond to district eigen values  $\lambda_1$ ,  $\lambda_2$  ......  $\lambda_r$  of an n x n matrix A, then the set{  $v_1$ ,  $v_2$ , ...... $v_r$  } is <u>linearly independent</u>

18. A scalar  $\lambda$  is an eigen value of an n x n matrix A if and only if  $|A - \lambda I| = 0$  has a non trivial solution.

19. If n x n matrices A and B are similar then they have same eigen values

20. If A is non invertible then |A| = 0